

SHRIMP III

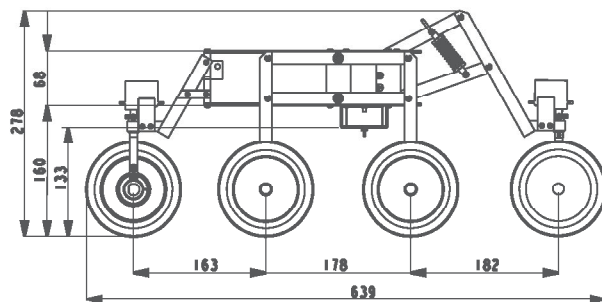


Mobile robotics in rough terrain has become a growing field for various applications:

- Space exploration
- Rescue in case of catastrophes
- Firefighting
- Remote inspection

The Shrimp III is a research platform with extended climbing abilities given by its passive mechanical configuration.

- Completely passive climbing structure
- Six motorized wheels
- Front and rear steered wheels
- Rotation - translation speed commands



Dimensions	639 x 428 x 278 mm
Weight	5.4 kg (with battery)
Payload	3 kg
Max speed	0.35 m/s
Stability	40° pitch, 40° roll
Interface	RS232



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